## History of the Paint Robot

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## Abstract

Starting in the sixties, we have seen a tremendous development of the robotics technology for paint applications. The first robots were however simple, easy to program and surprisingly reliable, thanks to superior craftsmanship carried out by the pioneers of the new trade (Fig. 1). Most references here are for painting robots, which is the division where this author has his experience.

Keywords: Paint robot, Robotics, Painting, Process system, Automotive paint

## 1. Introduction

A paint robot system consists of the manipulator, the controller and the teach pendant unit (TPU) (Fig. 2). In addition, most paint robots

Fig. 1 1967: The first working prototype.

2015年 1 月22日受付 Tormod Henne ABB AS (Nordlysvegen 7, 4340 Bryne Norway) TERADA Masaru ABB 株式会社 オートメーション・モーション事業部 ロボティクス部門 塗装機器部 have a process system that controls the fluid to be applied (Fig. 3). Furthermore, there is an in-

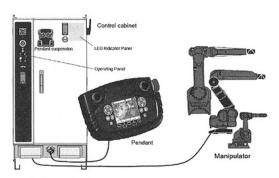


Fig. 2 Main components of a robot system

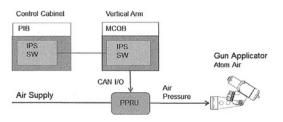


Fig. 3 Principles of Applicator Control.

PIB: Paint Interface Board, MCOB:

Manipulator Control Board, IPS: Integrated

Process System, PPRU: Proportional

Pressure Regulator Unit